The \*\*th Summit Meeting of

the Pacific-Asian Robotics Society Union (PARSU)

Date: Thursday, Oct. 1, 2015

Time: 11:00 – 12:45

Place: Room #12,

East side of 1st floor in Congress Center Hamburg (CCH), Germany (IROS 2015 site)

Agenda

1. Greeting and self-introduction

2. Approval of the minutes of PARSU-SM 2014

3. Report of current status of each member society

* [RSJ: Robotics Society of Japan] (Japan)
* [ARAA: Australian Robotics and Automation Association] (Australia and New Zealand)
* [CAA: Chinese Association of Automation] (China)
* [KROS: Korea Robotics Society] (Korea)
* [RSS: Robotics Society of Singapore] (Singapore)
* [RST: Robotics Society of Taiwan] (Taiwan)
* [TRS: Thai Robotics Society] (Thailand):
* [RSI: Robotics Society of India] (India); attend at 12:05

4. Discussion of hosting future PARSU-SMs

[Proposal for hosting PARSU summit meeting]

Basic rule from 2016 is:

* When IROS is held in the PARSU member country, the local society hosts the PARSU summit meeting at IROS site.
* Offer of hosting summit meeting is welcome, and if there is no specific offer, then KROS and RSJ host the summit meeting in turn, basically.
* Hosting includes arranging the meeting place and lunch, announcement of the meeting, and their budget.
* The host society is decided in the PARSU summit meeting two years in advance.

[Example if the above rule is applied]

* IROS2014 (Chicago, USA): KROS [fixed]
* IROS2015 (Hamburg, Germany): RSJ [fixed]
* IROS2016 (Daejeong, Korea): KROS [fixed]
* IROS2017 (Vancouver, Canada): open (candidate: RSJ)
* IROS2018 (Madrid, Spain): open (candidate: KROS)
* IROS2019 (Asia): open (candidate: RSJ)

5. Confirmation of MOU draft

6. Open discussion

7. Next meeting, closing remark, photograph

List of participants (in alphabetical order of member societies)

[ARAA: Australian Robotics and Automation Association] (Australia and New Zealand)

- Matthew Dunbabin (immediate past president of the ARAA, Queensland University of Technology, Australia)

[CAA: Chinese Association of Automation] (China)

- LIU Lianqing (Shenyang Institute of Automation, China)

[KROS: Korea Robotics Society] (Korea)

- Chul-Goo Kang (president of KROS, Konkuk University, Seoul)

- Hyouk Ryeol Choi (vice President of KROS, Sungkyunkwan University, Seoul)

- Jaeheung Park (board member of KROS, Seoul National University, Seoul)

[RSI: Robotics Society of India] (India)

- Madhav Krishna (International Institute of Information Technology (IIT) Kanpur, India)

[RSJ: Robotics Society of Japan] (Japan)

- Atsuo Takanishi (president of RSJ, Waseda University)

- Toshihiro Swawa (vice president of RSJ, Yaskawa Electric Co.)

- Takashi Yoshimi (vice president of RSJ, Shibaura Institute of Technology)

- Masahiro Okada (director of international relations of RSJ, Tokyo Institute of Technology)

- Yuji Hosoda (director of general affairs and secretary-general of RSJ, RSJ)

[RSS: Robotics Society of Singapore] (Singapore)

- Ryad Chellali (Nanjing Tech University, China)

[RST: Robotics Society of Taiwan] (Taiwan)

- Ren C. Luo (National Taiwan University, Taiwan)

[TRS: Thai Robotics Society] (Thailand):

- Phongsaen PITAKWATCHARA (Chulalongkorn University, Thailand)

- Nattee Niparnan (Chulalongkorn University, Thailand)

- Surat Kwanmuang (Chulalongkorn University, Thailand)

[VRA: Vietnam Association of Robotics] (Vietnam):

(nobody)